

babel
babel2008/03/16stringencnameref[2012/07/28]
seminar

A Simple Planning Problem for COVID-19 Lockdown

Fernando Alvarez

University of Chicago

David Argente

Pennsylvania State

Francesco Lippi

LUISS and EIEF

ANCE – Virtual Seminar

May 15, 2020

Overview

- ▶ Adopt (S, I, R) dynamic epi model: $S(t) \rightarrow I(t) \rightarrow R(t)$
- ▶ Contagion through social interactions implies externalities
- ▶ Planner's Problem: trade-off PV economic activity vs "value of life"

Overview

- ▶ Adopt (S, I, R) dynamic epi model: $S(t) \rightarrow I(t) \rightarrow R(t)$
- ▶ Contagion through social interactions implies externalities
- ▶ Planner's Problem: trade-off PV **economic activity** vs “**value of life**”
- ▶ Model Key Features:
 - (1) **Congestion** of health-care affects fatality rate: $\phi(I)$
 - (2) **Lockdown** affects infected (I) and susceptible (S) and....:
 -with **Antibody Test**: R can be identified & thus not in lockdown
 -w/o **Antibody Test**: R must be in lockdown.
 - (3) Analyze extension with **Test-Trace-Quarantine** (TTQ)

Overview

- ▶ Adopt (S, I, R) dynamic epi model: $S(t) \rightarrow I(t) \rightarrow R(t)$
- ▶ Contagion through social interactions implies externalities
- ▶ Planner's Problem: trade-off PV **economic activity** vs "value of life"
- ▶ Model Key Features:
 - (1) **Congestion** of health-care affects fatality rate: $\phi(I)$
 - (2) **Lockdown** affects infected (I) and susceptible (S) and....:
 -with **Antibody Test**: R can be identified & thus not in lockdown
 -w/o **Antibody Test**: R must be in lockdown.
 - (3) Analyze extension with **Test-Trace-Quarantine (TTQ)**
- ▶ Results:
 - Identify **main determinants for lockdown intensity and duration**
 - Quantify **welfare costs of lockdown** (forgone GDP and lost lives)
 - Quantify benefits of **Testing** and of **TTQ**

Related econ. literature

Many recent studies, some closely related, most date March / April 2020

- ▶ Planning problem: Hansen-Troy 2011; Eichenbaum,Rebelo and Trabandtz; Gonzalez-Eiras and Niepelt; Kaplan, Moll and Violante; Piguillem and Shi
- ▶ Equilibria with (endogenous) social distancing: Fenichel (2013); Toxvaerd (2015); Jones, Philippon and Venkateswaran ; Farboodi,Jarosch,Shimer
- ▶ forecasting, measurement and cost valuations : Atkeson; Bassetto; Hall,Jones,Klenow; Stock; Jones-Villaverde

Setup: SIR model with Lockdown Policy

- Total Population at t : Susceptible + Infected + “Recovered”

$$N(t) = \mathcal{S}(t) + \mathcal{I}(t) + \mathcal{R}(t)$$

- Lockdown fraction $L(t) \in [0, \bar{L}]$ of $\mathcal{S}(t) + \mathcal{I}(t)$,
- Susceptible become infected by contacting I at rate: β

$$\dot{\mathcal{S}}(t) = -\beta \mathcal{S}(t) \times \mathcal{I}(t)$$

- Infected transit to “recovered” at rate γ

$$\dot{\mathcal{I}}(t) = \beta \mathcal{S}(t) \times \mathcal{I}(t) - \gamma \mathcal{I}(t)$$



Setup: SIR model with Lockdown Policy

- ▶ Total Population at t : Susceptible + Infected + “Recovered”

$$N(t) = \mathcal{S}(t) + \mathcal{I}(t) + \mathcal{R}(t)$$

- ▶ Lockdown fraction $L(t) \in [0, \bar{L}]$ of $\mathcal{S}(t) + \mathcal{I}(t)$, with effectiveness $\theta \in (0, 1)$
- ▶ Susceptible become infected by contacting I at rate: $\beta(1 - \theta L(t))^2$

$$\dot{\mathcal{S}}(t) = -\beta \mathcal{S}(t) \times \mathcal{I}(t) (1 - \theta L(t))^2$$

- ▶ Infected transit to “recovered” at rate γ

$$\dot{\mathcal{I}}(t) = \beta \mathcal{S}(t) \times \mathcal{I}(t) (1 - \theta L(t))^2 - \gamma \mathcal{I}(t)$$

- ▶

Setup: SIR model with Lockdown Policy

- Total Population at t : Susceptible + Infected + “Recovered”

$$N(t) = S(t) + I(t) + R(t)$$

- Lockdown fraction $L(t) \in [0, \bar{L}]$ of $S(t) + I(t)$, with effectiveness $\theta \in (0, 1)$
- Susceptible become infected by contacting I at rate: $\beta(1 - \theta L(t))^2$

$$\dot{S}(t) = -\beta S(t) \times I(t)(1 - \theta L(t))^2$$

- Infected transit to “recovered” at rate γ

$$\dot{I}(t) = \beta S(t) \times I(t)(1 - \theta L(t))^2 - \gamma I(t)$$

- A fraction of the infected die

$$-\dot{R}(t) = \underbrace{[\varphi + \kappa I(t)] \gamma}_{\phi(I)} \times I(t)$$

Planner's dynamic control problem

- ▶ Planner chooses path $\{L(t)\}$ to minimize the present discounted value:

$$V(S, I) = \min_{L(t)} \int_0^{\infty} e^{-(r+\nu)t} \left(\underbrace{w L_t [\tau(S_t + I_t) + 1 - \tau]}_{\text{GDP loss}(t)} + \underbrace{\phi(I_t) I_t \times [vsI]}_{\text{deaths}(t) \times \text{value of life}} \right) dt$$

subject to the law of motion of S and I shown before.

- ▶ Two technologies for lockdown
 - w. Test ($\tau = 1$) : lockdown to $(S + I)$, not to R
 - w/o Test ($\tau = 0$): lockdown to $(S + I + R)$

Bellman equation

Value function $V(S, I)$ for all $0 \leq S + I \leq 1$ solves:

$$(r + \nu)V(S, I) = \min_{L \in [0, \bar{L}]} w L [\tau(S + I) + 1 - \tau] + \phi(I) I [vsl] \\ - [\beta SI(1 - \theta L)^2] \partial_S V(S, I) + [\beta SI(1 - \theta L)^2 - \gamma I] \partial_I V(S, I)$$

Initial condition $N(0) = 1$, $I(0) = \epsilon$ and $S(0) = 1 - \epsilon$.

Value function domain $(S, I) \in (0, 1) \times (0, 1)$ s.t. $S + I < 1$

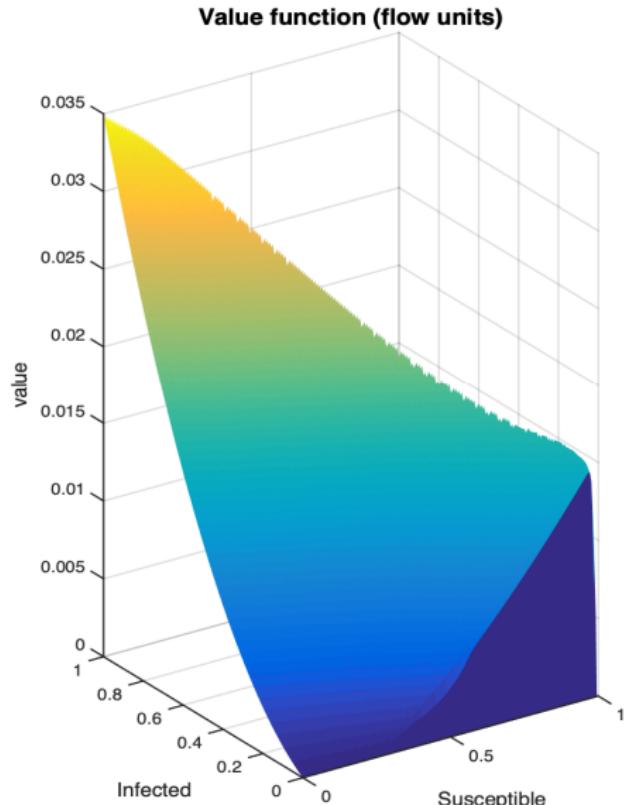
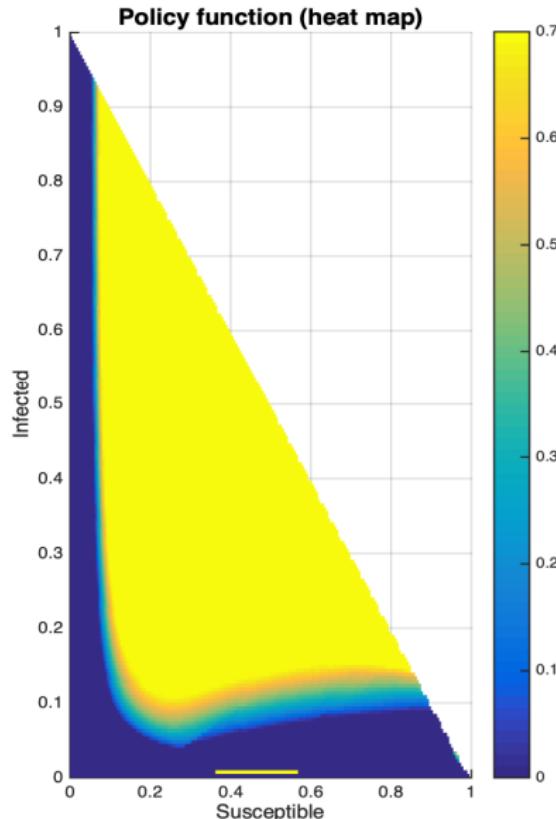
Boundary condition at $I = 0, \forall S \in (0, 1)$: $V(S, 0) = 0$

Boundary condition at $S = 0, \forall I \in (0, 1)$: $V(0, I) = vsl \cdot \left(\frac{\varphi\gamma}{r+\nu+\gamma} + \frac{\kappa\gamma I}{r+\nu+2\gamma} \right) \cdot I$

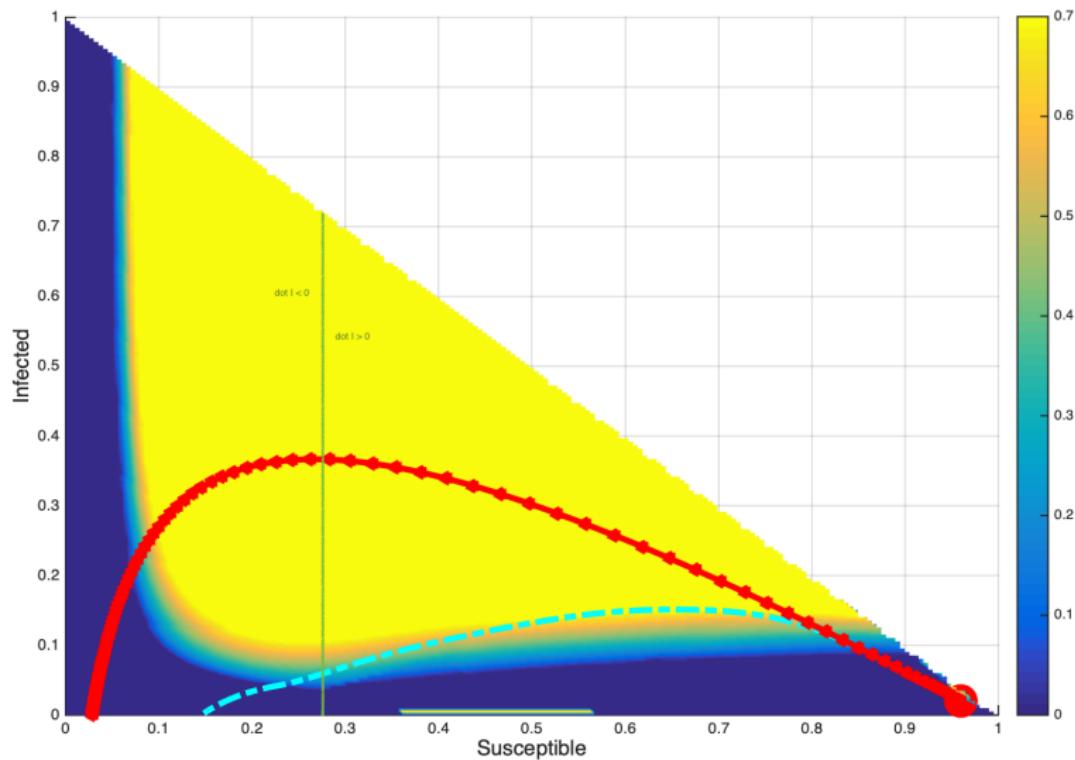
Baseline parameters

| Parameter | Value | Definition |
|------------------|-------------------|--|
| EPI PARAMETERS | | |
| β | $1/5 \times 365$ | Annual Transmission rate if (uncontrolled) |
| γ | $1/18 \times 365$ | Annual rate at which active cases “recover” |
| φ | 0.01 | Deaths per active case (per day) at zero infections. |
| κ | 0.05 | Implies a 3 % fatality rate with 40 % infected. |
| OTHER PARAMETERS | | |
| r | 0.05 | Annual interest rate 5 percent. |
| ν | 0.667 | Prob rate vaccine + cure (exp. duration 1.5 years) |
| L | 0.70 | 1 - GPD share health, retail, gov., utilities, food mfg. |
| θ | 0.5 | Lockdown Effectiveness (0 is ineffective) |
| vsl | 20 | Value of Statistical Life = $20 \times$ GPD per capita (Jones, Hall and Klenow) |

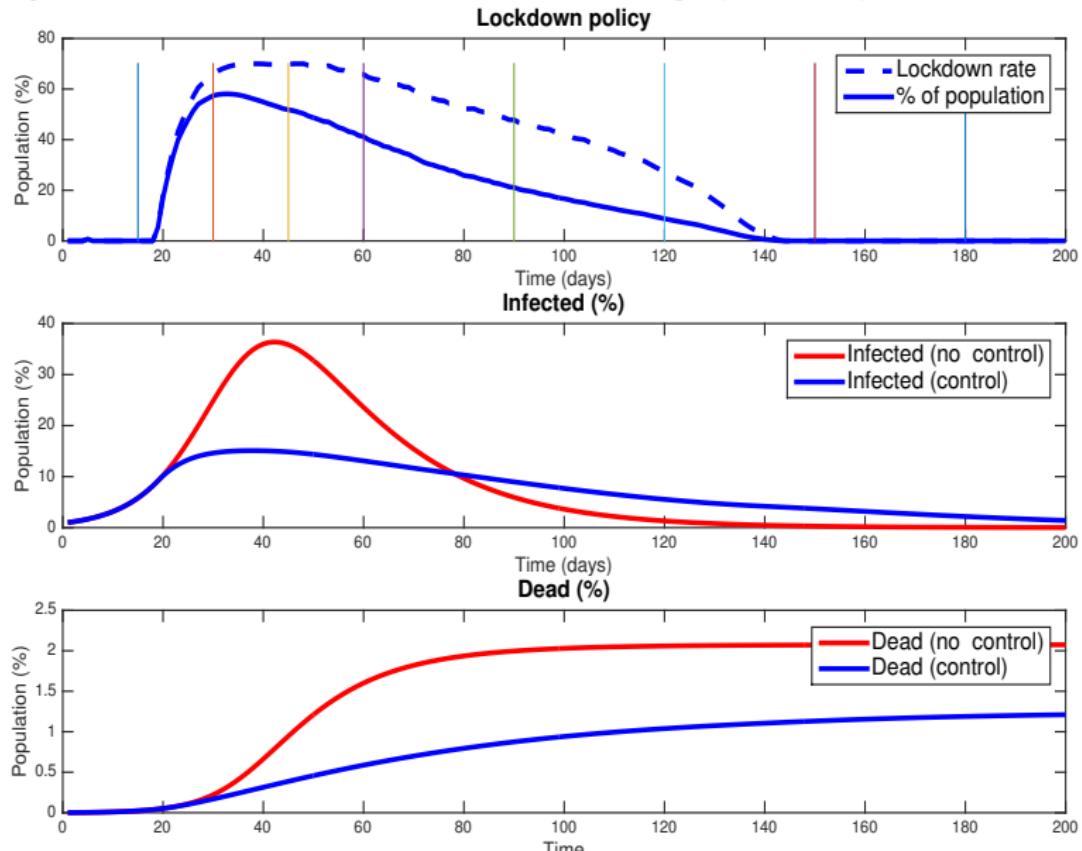
Value Function and Optimal Policy



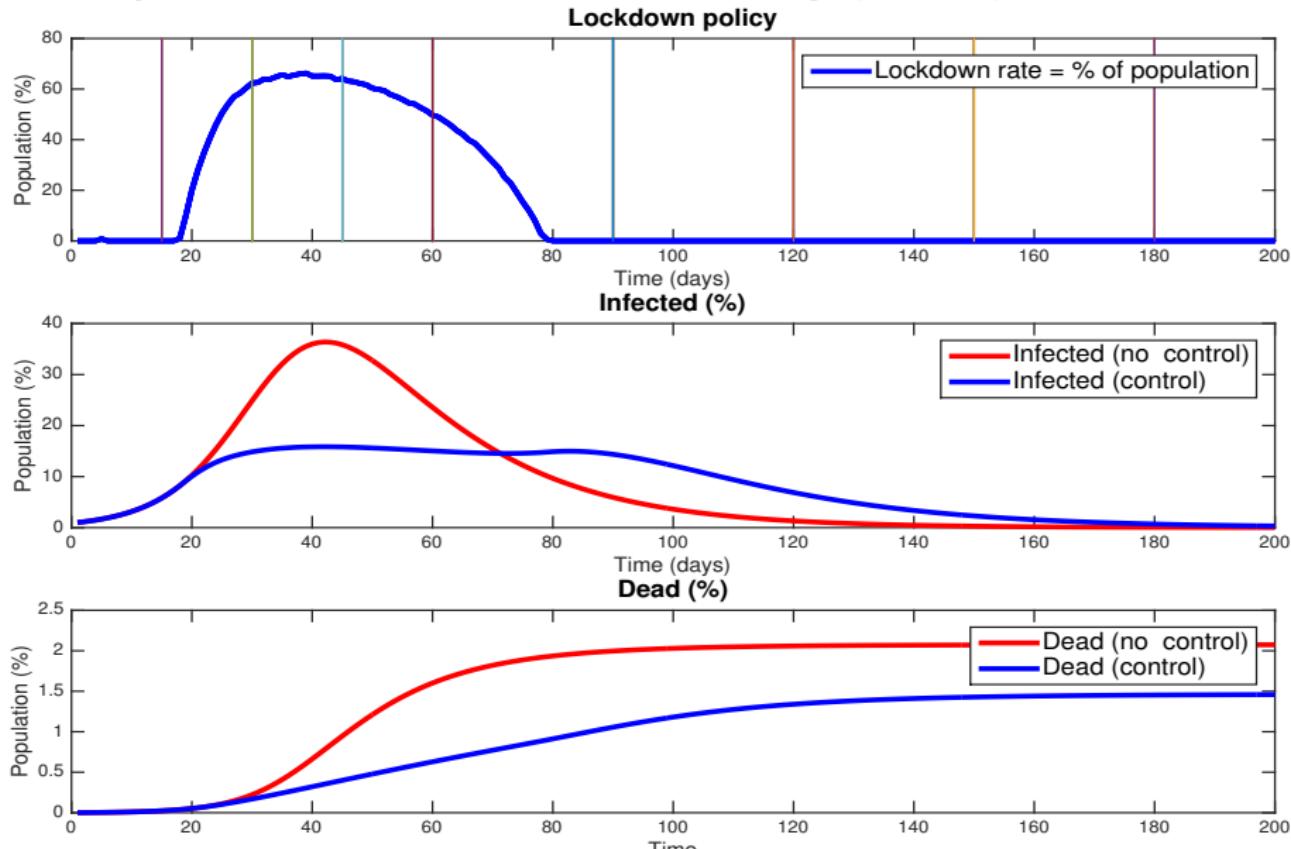
Optimal Policy, phase diagram (bench., $I(0) = 0.01$)



Time path: Benchmark w. Testing ($\tau = 1$)

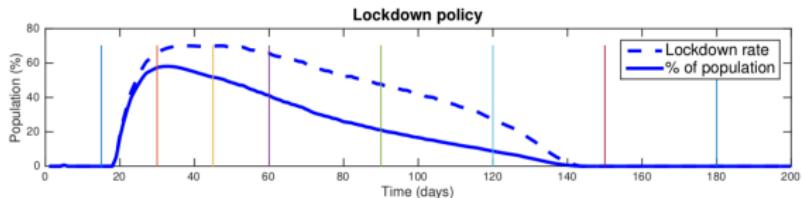


Time path: Benchmark w/o Testing ($\tau = 0$)

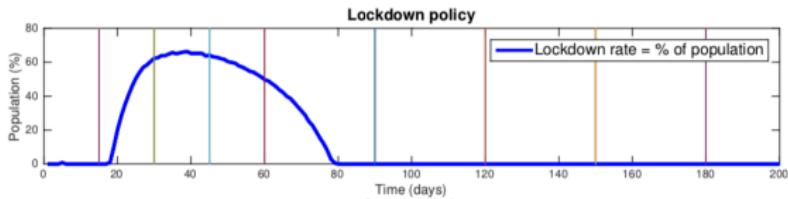


Welfare effect of Testing: 2% of one year's GDP

Panel A – Case w / testing ($\tau = 1$)



Panel B – Case w/o testing ($\tau = 0$)



Remarks on the optimal lockdown paths:

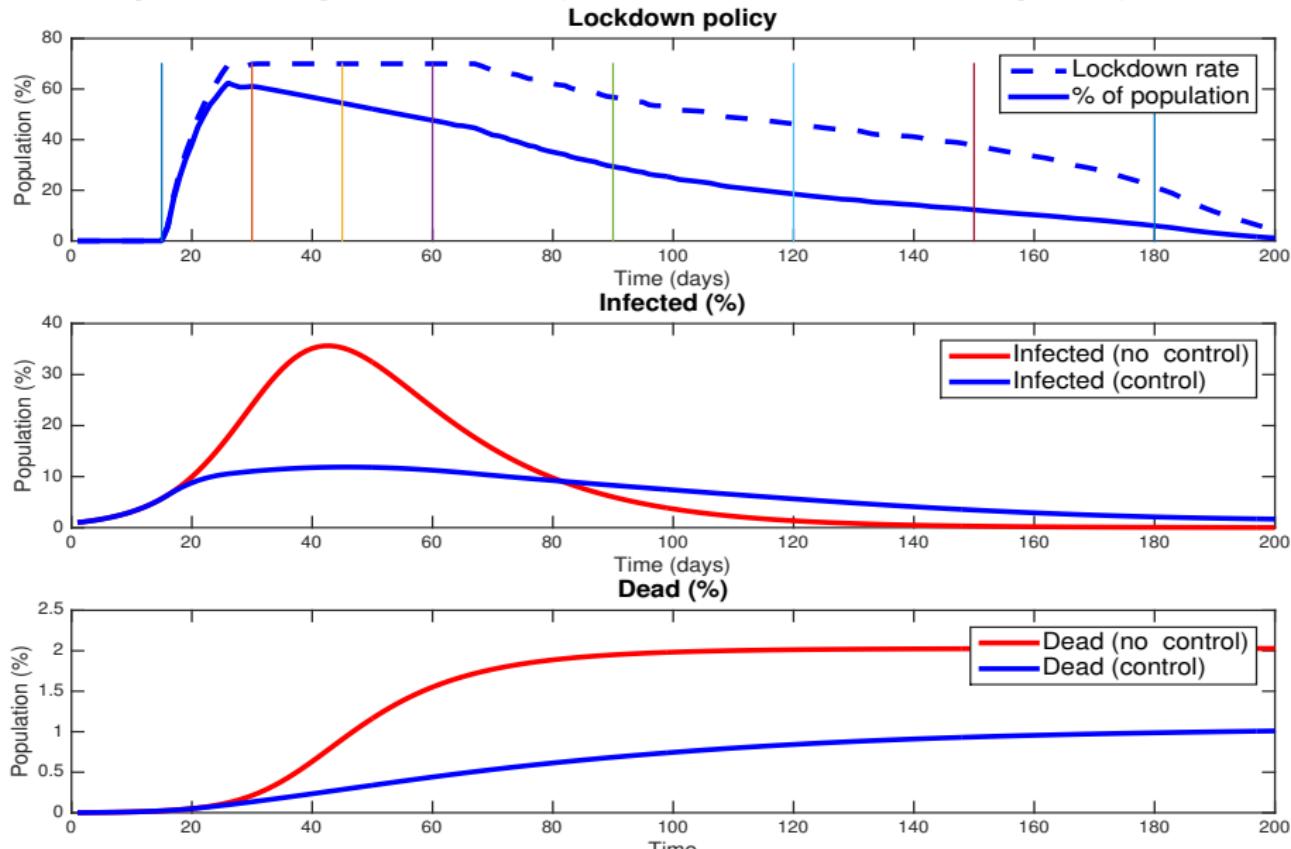
- 1- Lckdn. much longer with testing, and ends gradually
- 2- Lckdn. ends abruptly w/o testing (large efficiency costs)
- 3- Lckdn.s comparable as total hours lost; but deaths higher w/o Test

Welf. Loss w. Test: Optimal policy vs. No Intervention

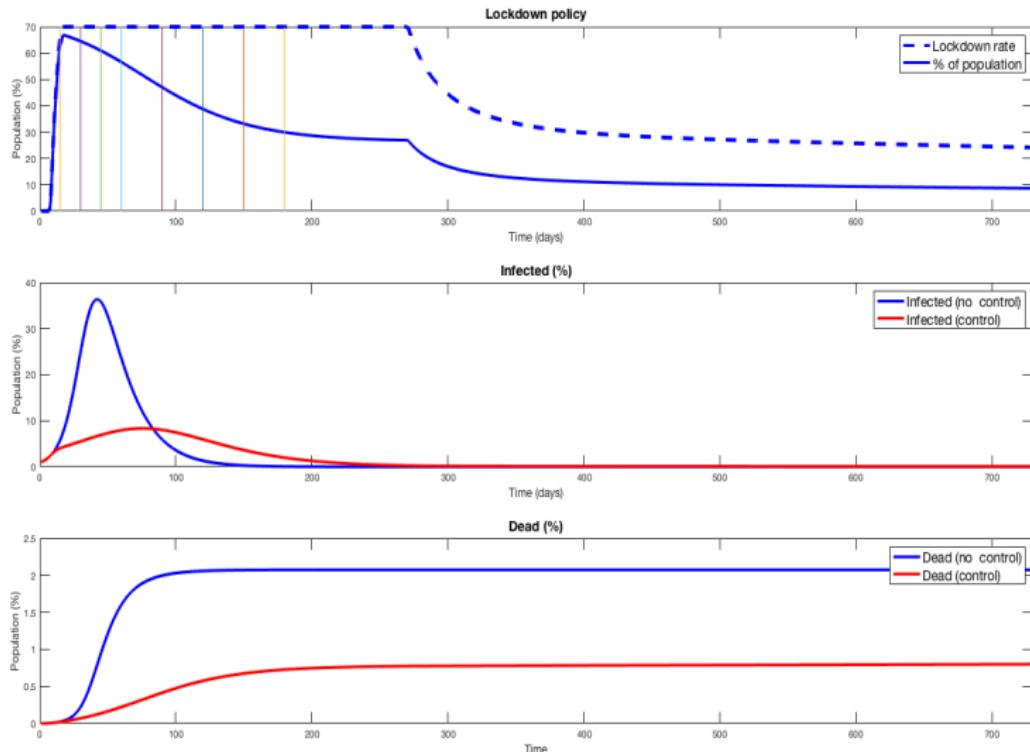
| Case | Optimal Policy Welfare Loss | Optimal Policy Output Loss | No Policy Welfare Loss |
|---|--------------------------------|-------------------------------|---------------------------|
| <i>Benchmark Case</i> | | | |
| Medium lock. effectiveness ($\theta=0.5$) | 1.5% | 0.4% | 1.9% |
| High lock. effectiveness ($\theta=0.7$) | 1.4% | 0.5% | 1.9% |
| <i>Alternative Values of Statistical Life (baseline is $20 \times$ GDP/capita)</i> | | | |
| $vsl = 30 \times$ GDP/capita | 2.0 % | 0.6 % | 2.8 % |
| $vsl = 80 \times$ GDP/capita | 3.7 % | 1.4 % | 7.5 % |
| <i>Constant fatality rate ($\kappa=0$)</i> | | | |
| Medium lock. effectiveness ($\theta=0.5$) | 0.9 % | 0.0 % | 0.9 % |
| High lock. effectiveness ($\theta=0.7$) | 0.9 % | 0.0 % | 0.9 % |

Multiply %'s by 20 to get cost as a fraction of one year's GDP

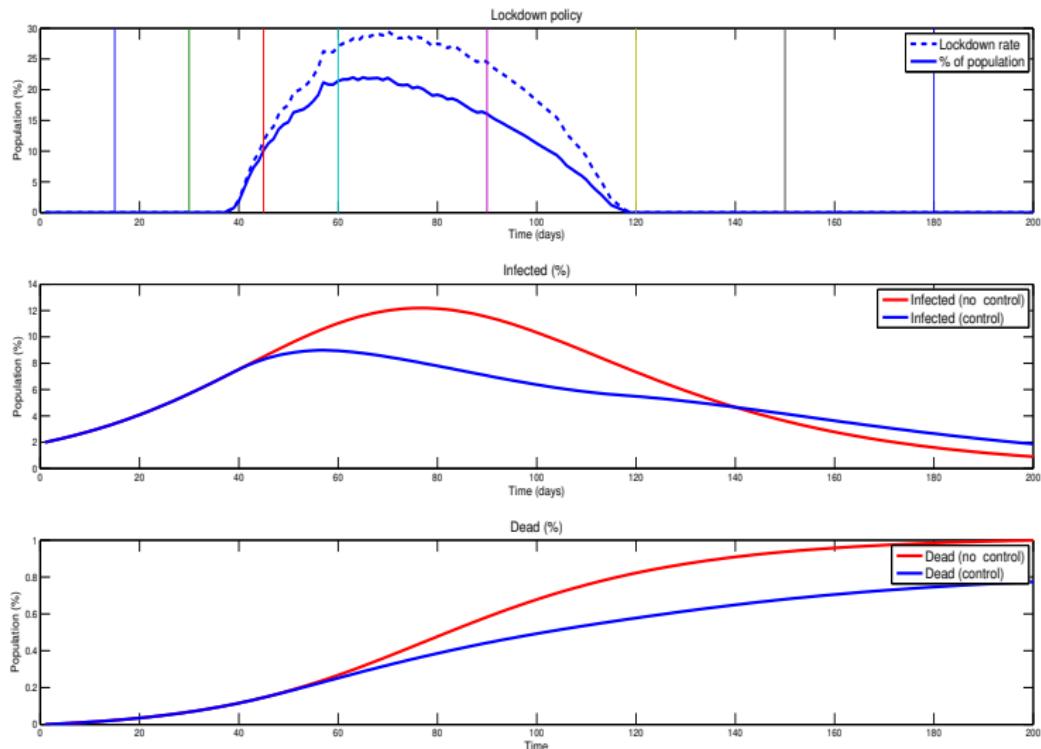
Time path, higher VSL ($vsI = 30 \times \text{GDP/capita}$)



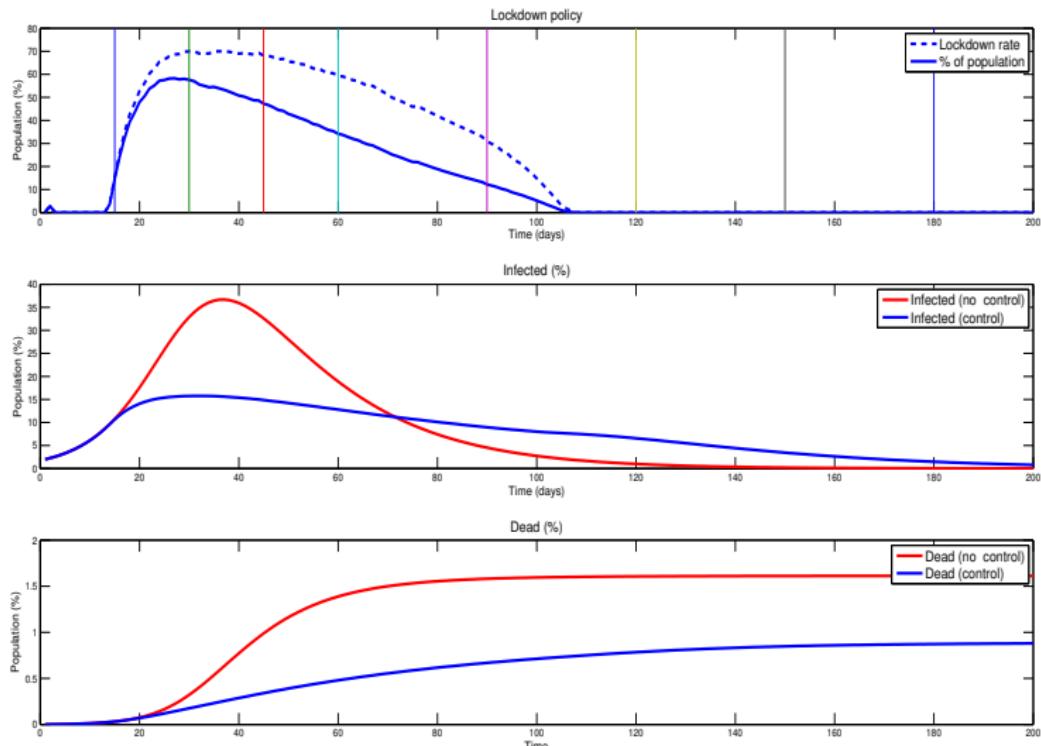
Time path: very high VSL ($vsl = 60 \times \text{GDP/capita}$)



Time path: Lower Transmission Rate ($\beta = 0.10$)



Time path: Lower Fatality Per Active Case ($\varphi = 0.005$)



More scenarios: NO test and lower lethality of virus

| Case | Optimal Policy | | No Policy Welfare Loss |
|---|----------------|-------------|---------------------------|
| | Welfare Loss | Output Loss | |
| <i>Benchmark Case w. Test</i> | | | |
| $vsl = 20 ; \beta = 0.20; \tau = 1; \varphi = 0.01$ | 1.5 % | 0.4 % | 1.9% |
| <i>Benchmark w/o Test</i> | | | |
| | 1.6 % | 0.4 % | 1.9 % |
| <i>Lower diffusion / Fatality rates</i> | | | |
| Slower diffusion ($\beta = 0.20/2$) | 0.8% | 0.1% | 0.8% |
| Lower fatality rates ($\varphi = 0.01/2$) | 1.1% | 0.4% | 1.5% |

Multiply %'s by 20 to get cost as a fraction of one year's GDP

Extension: Testing, Tracing and Quarantine (TTQ)

New control T : people sent to quarantine (flow);

$$\dot{S}_t = -\beta S_t(I_t - Q_t)(1 - \theta L_t)^2$$

$$\dot{I}_t = \beta S_t(I_t - Q_t)(1 - \theta L_t)^2 - \gamma I_t$$

$$\dot{Q}_t = T_t - \gamma Q_t$$

The planner minimizes (Assume $\tau = 1, \kappa = 0$):

$$V(S_0, I_0, Q_0) = \min_{\{L_t, T_t\}} \int_0^{\infty} e^{-(r+\nu)t} \left\{ w L_t [(S_t + I_t - Q_t)] + w Q_t + \right. \\ \left. + c(T_t; S_t, I_t - Q_t) + v s l \varphi \gamma I_t \right\} dt$$

Direct cost of test-tracing T people:

$$c(T, S, I - Q) = \frac{\alpha}{2} \left(T \underbrace{\left(\frac{S + I - Q}{I - Q} \right)^{1-\zeta}}_{\# \text{ "task" per } T} \right)^2$$

Effectiveness of tracing: $\zeta \in [0, 1]$;

Extension: Testing, Tracing and Quarantine (TTQ)

New control T : people sent to quarantine (flow); Define $X_t \equiv I_t - Q_t$

$$\dot{S}_t = -\beta S_t (I_t - Q_t) (1 - \theta L_t)^2$$

$$\dot{I}_t = \beta S_t (I_t - Q_t) (1 - \theta L_t)^2 - \gamma I_t$$

$$\dot{Q}_t = T_t - \gamma Q_t$$

The planner minimizes (Assume $\tau = 1, \kappa = 0$):

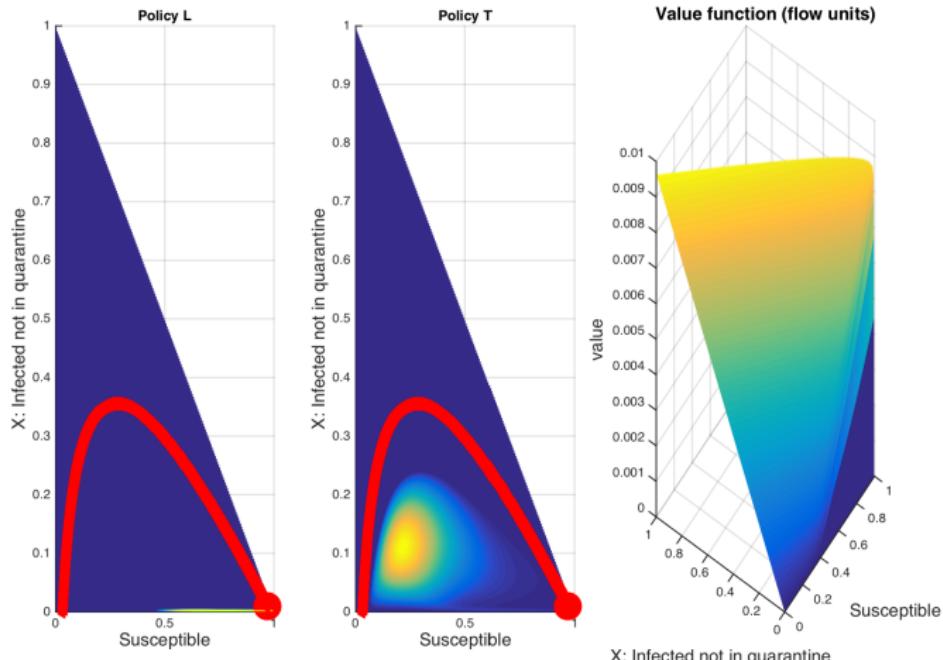
$$V(S_0, I_0, Q_0) = \min_{\{L_t, T_t\}} \int_0^{\infty} e^{-(r+\nu)t} \left\{ w L_t [(S_t + I_t - Q_t)] + w Q_t + \right. \\ \left. + c(T_t; S_t, I_t - Q_t) + vsl \varphi \gamma I_t \right\} dt$$

Direct cost of test-tracing T people:

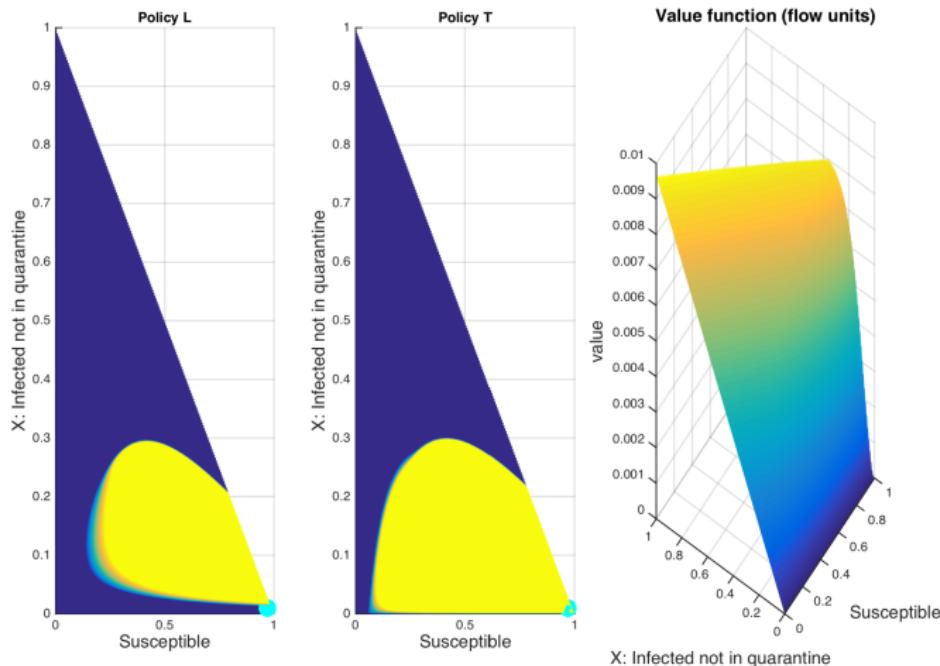
$$c(T, S, I - Q) = \frac{\alpha}{2} \left(T \underbrace{\left(\frac{S + I - Q}{I - Q} \right)^{1-\zeta}}_{\# \text{ "task" per } T} \right)^2$$

Effectiveness of tracing: $\zeta \in [0, 1]$; Prop: $V(S, I, Q) = v(S, X) + Q \frac{w + vsl \varphi \gamma}{r + \nu + \gamma}$

TTQ - Random Tracing ($\zeta = 0$)

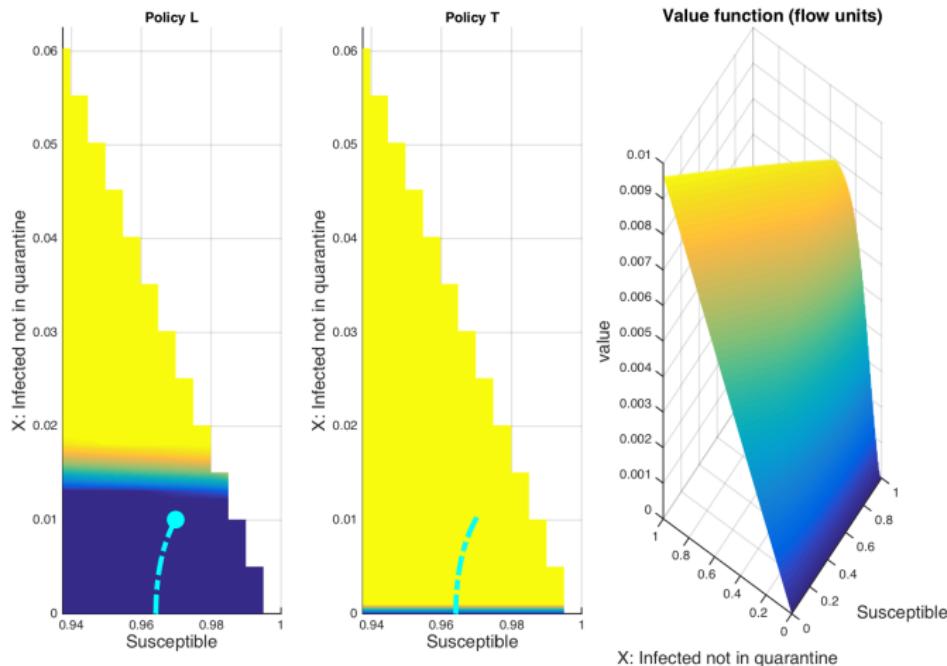


TTQ - Perfect Tracing ($\zeta = 1$)



Perfect tracing reduces welfare losses by 4 times (from 0.9% to 0.2% GDP)

TTQ - Perfect Tracing ($\zeta = 1$) – Zoom on details



Perfect tracing reduces welfare losses by 4 times (from 0.9% to 0.2% GDP)

Conclusions

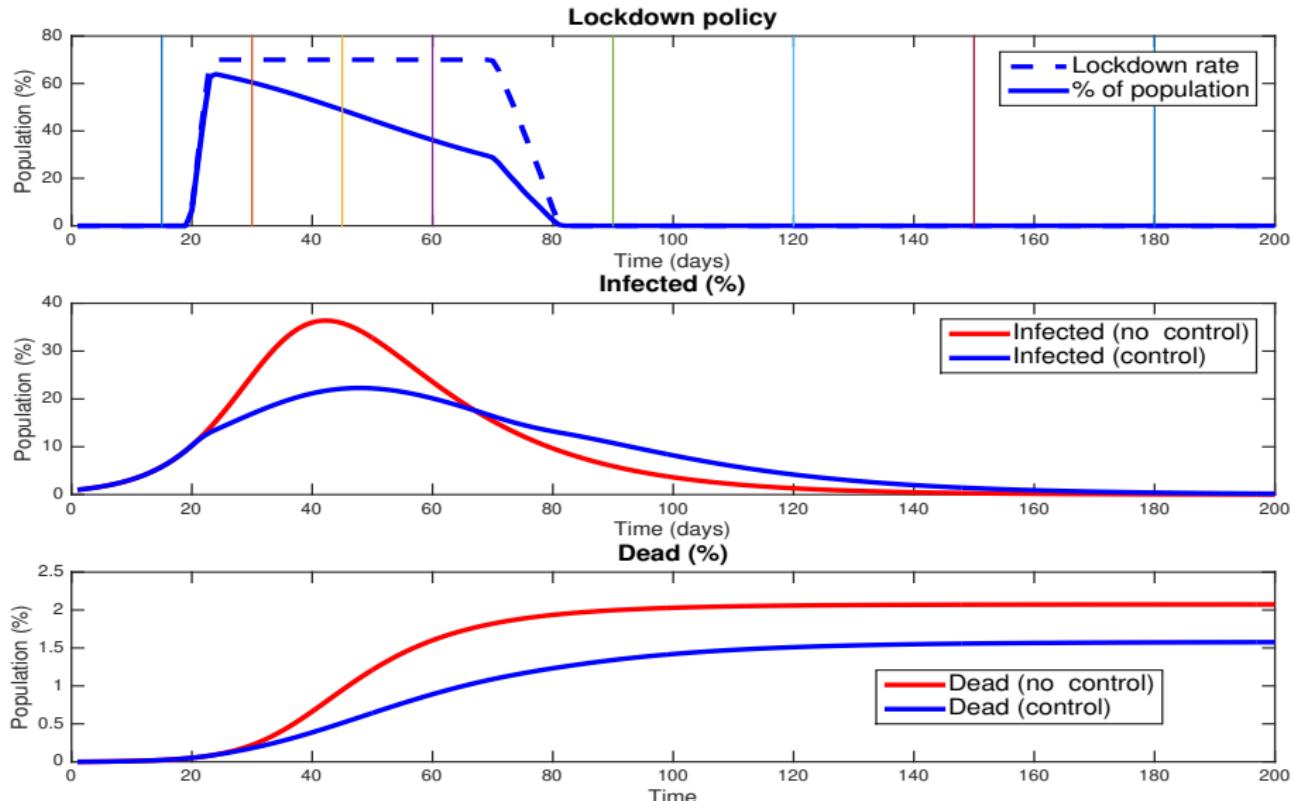
- ▶ Simple framework to analyze trade off of lockdown
- ▶ COVID19 is very costly: PV of forgone output is approx 8% annual GDP
- ▶ The benefit of a test for the recovered is large (2% GDP)
- ▶ TTQ policy can be valuable with effective tracing

Conclusions

- ▶ Simple framework to analyze trade off of lockdown
- ▶ COVID19 is very costly: PV of forgone output is approx 8% annual GDP
- ▶ The benefit of a test for the recovered is large (2% GDP)
- ▶ TTQ policy can be valuable with effective tracing
- ▶ Main forces behind optimal lockdown intensity and duration
 - ▶ gradient of fatality rate $\phi(I)$
 - ▶ statistical value of life
- ▶ Open questions
 - ▶ Parameters? hard to measure, fatality rates, β , congestion, ...
 - ▶ Richer model: Non linear cost of lockdown, persistent effects
 - ▶ Equilibrium: self-isolation, alternative matching framework
- ▶ Even w/small state space, tricky computation at the border of state space.

Additional slides

Time path: Low effectiveness ($\theta = 0.3$ vs $\theta = 0.5$)



Time path: Lower VSL ($vsl = 10 \times$ ann. GDP/capita)

